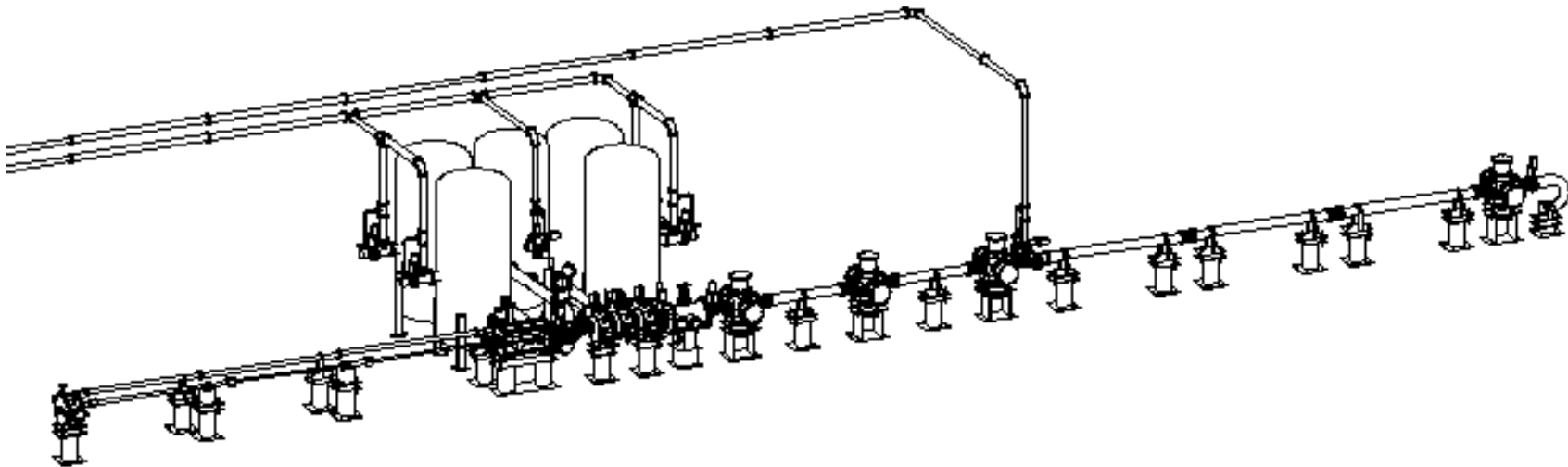




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Status of Target Injector, In-Chamber Tracking, and Electromagnetic Injector



**Ronald Petzoldt, Dan Goodin, Neil Alexander, Gottfried Besenbruch,
Walt Egli, Leslie Evans, John Follin, Dane Fricker, Chuck Gibson, Mike
Gouge, Michael Hollins, Kevin Jonestrask, and Dennis Lieurance**

HAPL Project Review

Pleasanton, CA November 13, 2001



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Overview/Summary

Status of injector

- Design status
- Selected examples of mechanical design
- Schedule overview

Analysis of tracking requirements based on chamber pressure

- Coefficient of drag
- Target displacement
- In-chamber tracking likely required for chamber pressure $> 10^{-4}$ Torr
- Methods of in-chamber tracking

Electromagnetic injector is being modeled as a backup to the gas gun

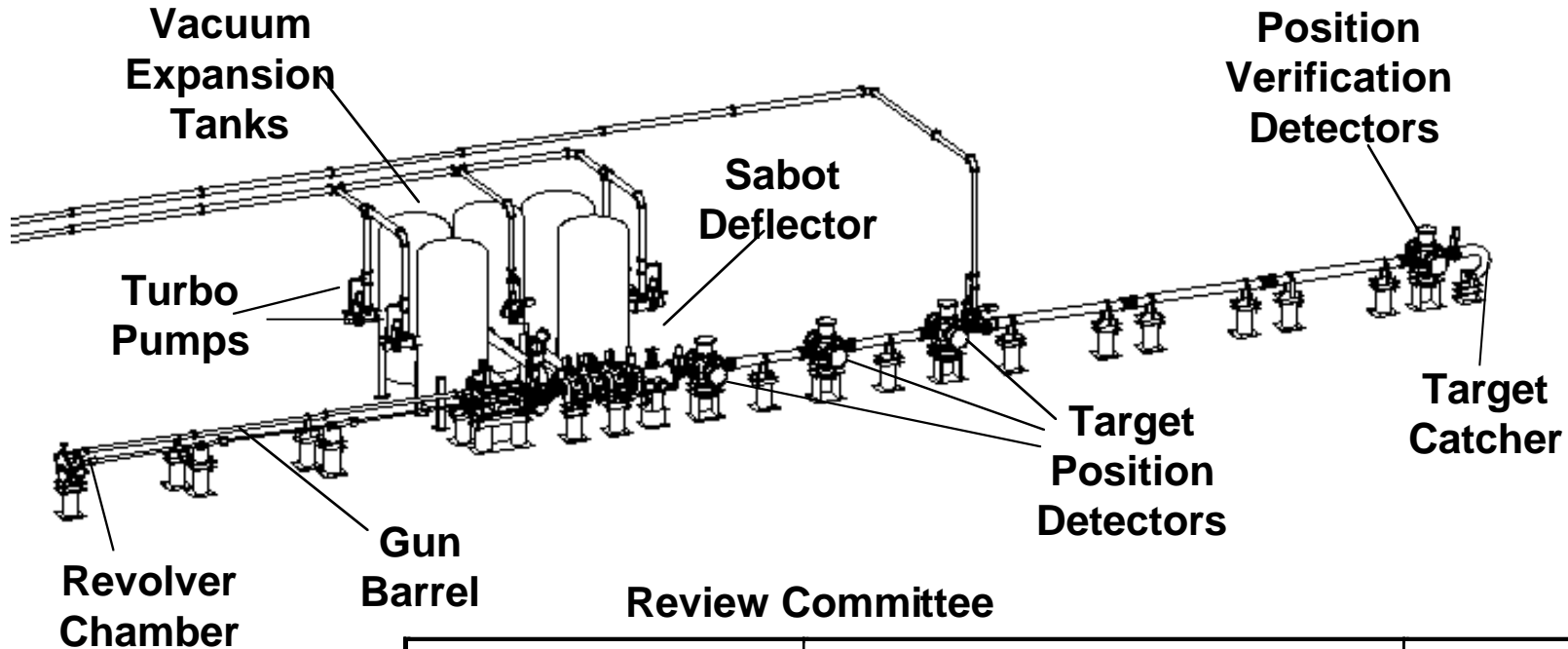
- Advantages for power plant use



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The Experimental Target Injection and Tracking System Final Design Review will be held at GA on 16 November



Name	Area of Expertise	Affiliation
Frederick Dahms	(Chairman)	Independent
Ted Torres	Computer and Control Systems	LANL/GA
Lance Lund	Mechanical Engineering	LLE Rochester
Rudi Klasen	Mechanical Engineering	GA
Pat Connors	Quality Assurance	GA

Final check of drawings and design documents prior to procuring equipment



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Detailed design work has been accomplished

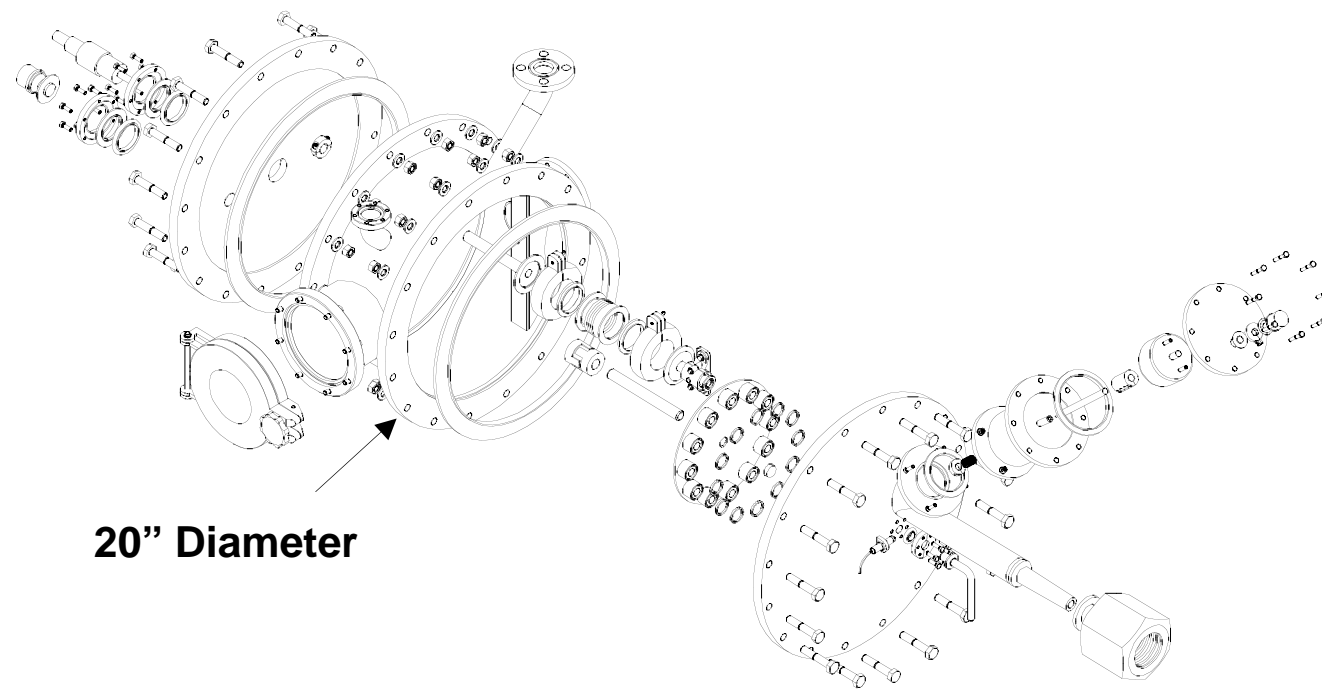
Document type		
Drawings		
PFD and P&ID		
Mechanical Assembly		
Weldment		
Control Block Diagram		
Electrical Schematic		
Miscellaneous		
Word Documents		
System Design Descriptions		
QAPD		
Technical Specifications		
Equipment/ instrument lists		
Miscellaneous docs		



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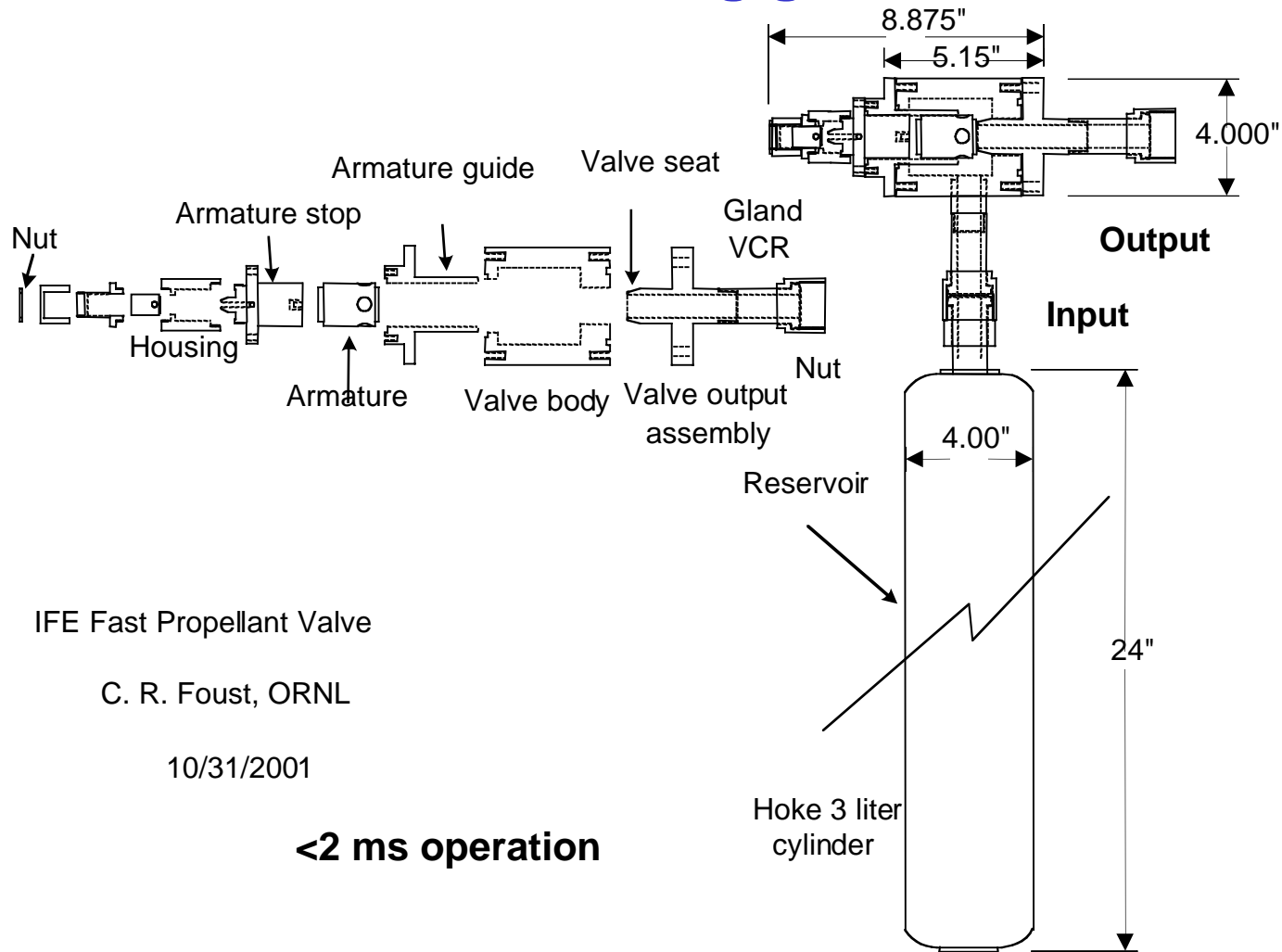


Design Example: Exploded view of revolver chamber assembly





Design Example: Fast acting gas valve



IFE Fast Propellant Valve

C. R. Foust, ORNL

10/31/2001

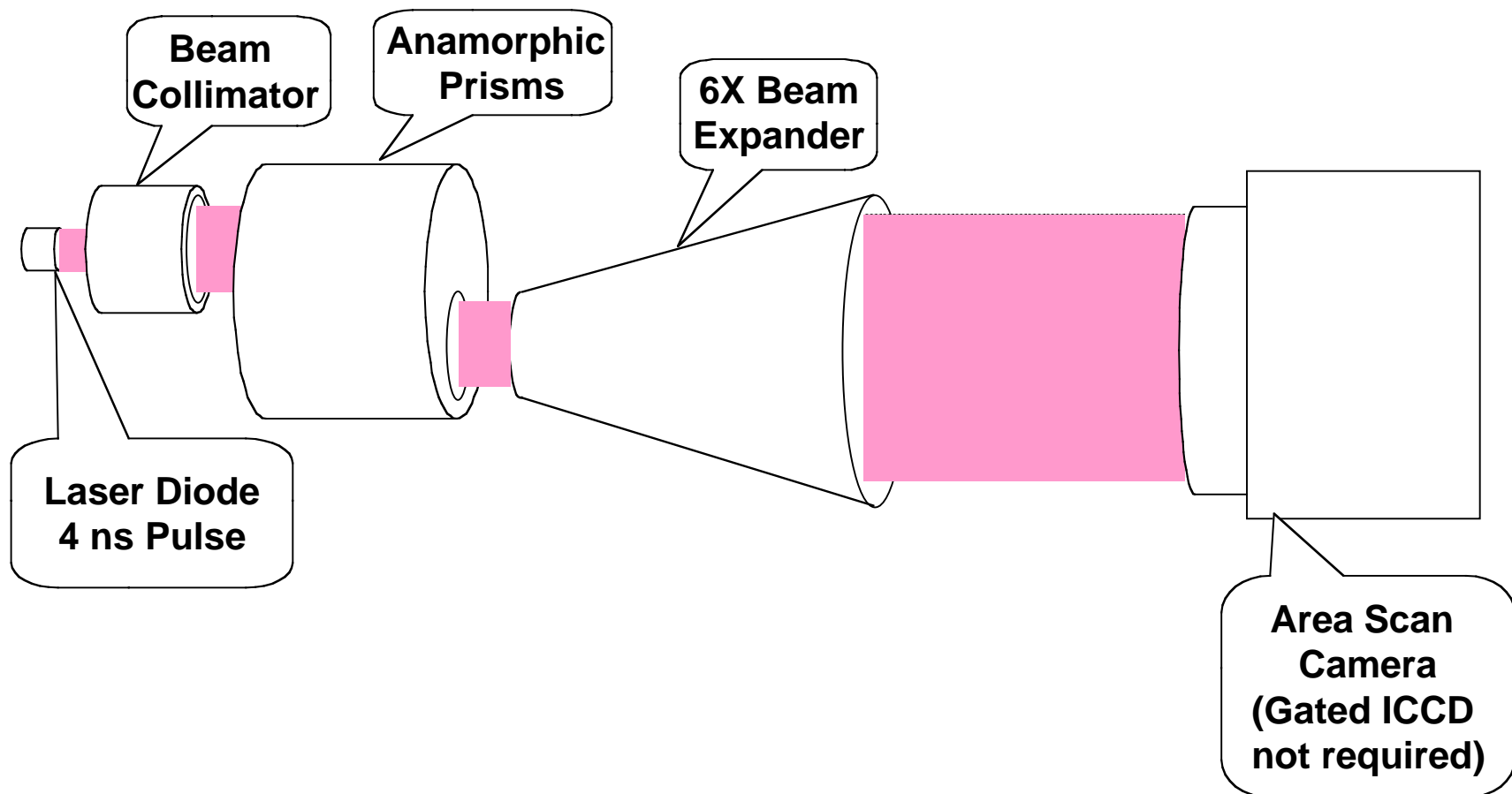
<2 ms operation



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A change from the PDR is use of pulsed laser illumination of position verification cameras



Simplified Target Fab/Injection 5-Year Plan

Target Injection

Injection Accuracy and Tracking
Data, Anal. and Modeling

NRL Target Physics

Prel. Target Designs | Target Analysis (Continuing)

Target Fabrication

Studies, R&D, Proof of Principle

IRE Plant Design →

Upgrade to Cryo

Cryo

	CY01	CY02	CY03	CY04	CY05
Final Design	—				
Procurement & Fabrication		—			
Assembly and Initial Shakedown			—		
Acquire Data, Modify Equipment to Optimize Results				—	
Doc. Results/Support IRE Decision				—	
Conceptual Design of Injector Upgrades (Cryo & High-Temp Equipment)				—	
Implement Cryo Upgrades					→

Target Baseline Design (NRL)

IRE Plant Design

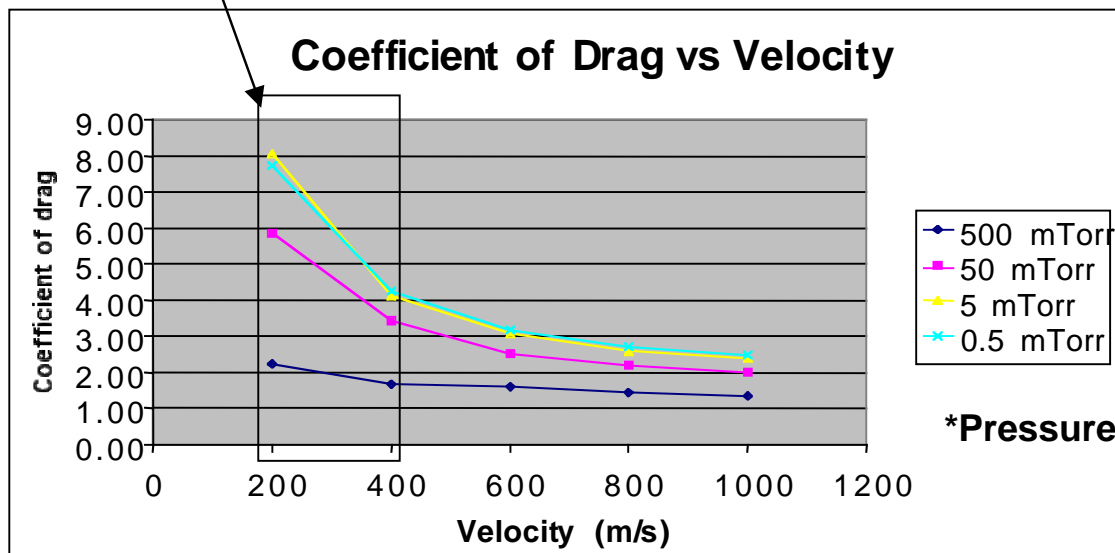
Engineering Prototype Development

FY 2001 | FY 2002 | FY 2003 | FY 2004 | FY 2005 | FY 2006 | FY2007



Significant drag occurs even at low chamber gas densities

Range of interest



$$F_D = C_D(0.5)\pi\rho r_t^2 v^2$$

*Pressures at standard temperature

Based on DSMC
drag force calculations

At lower (<~ 5 mTorr) pressures C_D does not change with density. Therefore the drag force increases linearly with density.

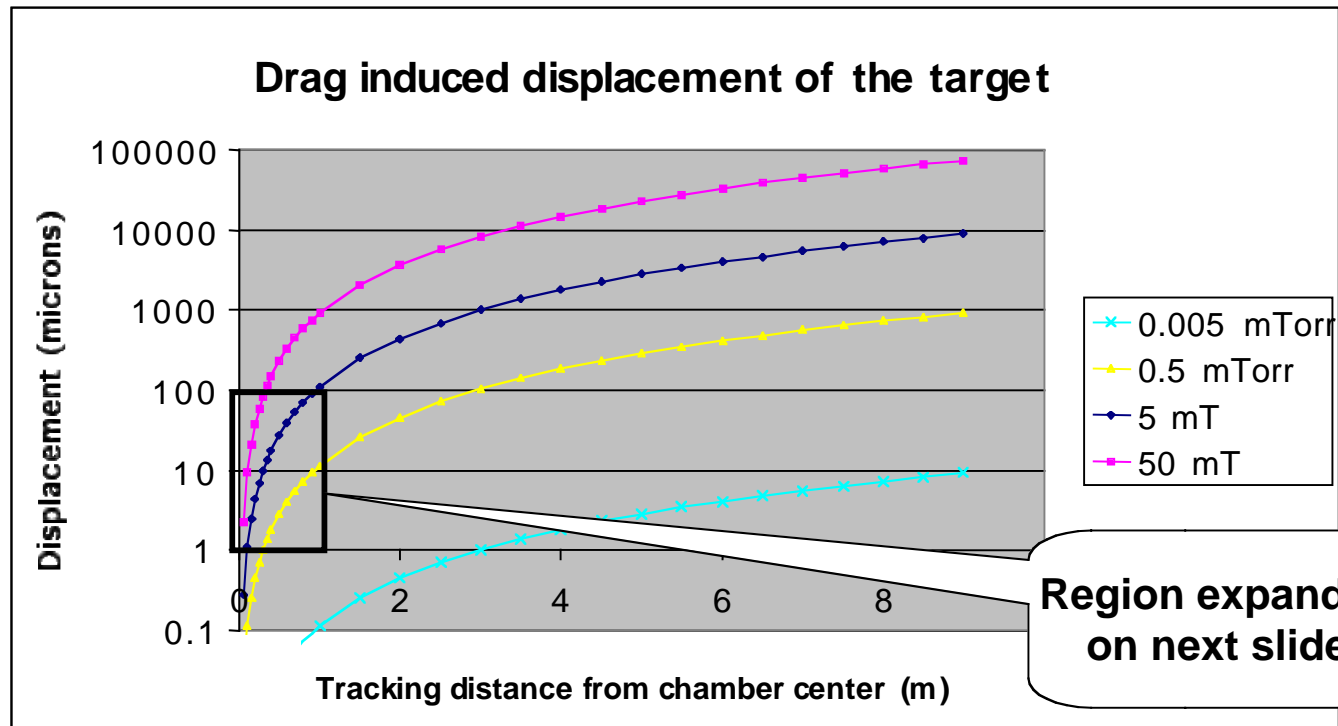
For low density (< 50 mTorr), the drag coefficient is cut in half as speed increases from 200 to 400 m/s. Therefore, $F_D \sim C_D v^2$ increases linearly rather than quadratically with speed.



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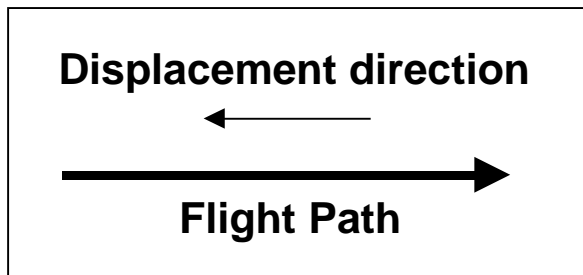


Drag induced target displacement is quite large even at modest operating pressures (i.e. 5 to 50 mTorr)



Assumptions:
Xe gas in chamber
Target speed = 400 m/s
2 mm radius target
4 mg target

Region expanded on next slide



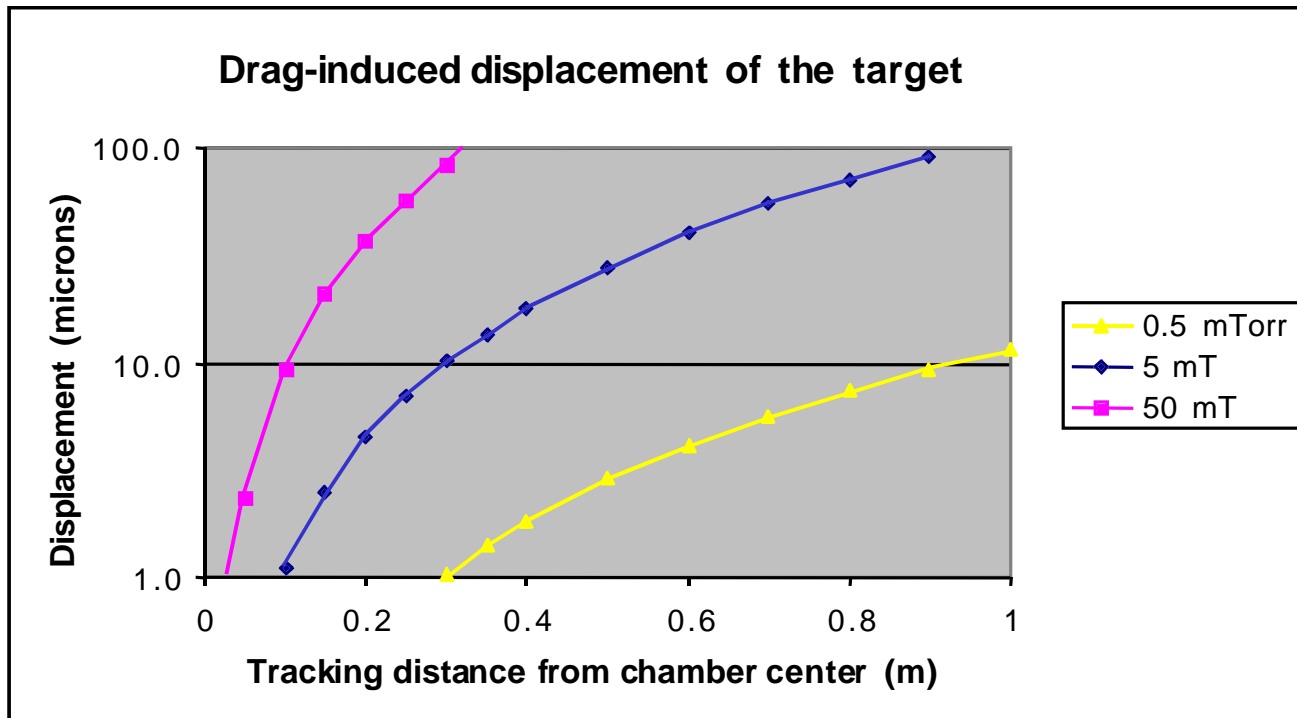
- Only external target tracking requires
- 1. Operate at $<5 \times 10^{-6}$ Torr or
- 2. Know pressure to $\pm 5 \times 10^{-6}$ Torr



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In-chamber tracking is required for higher pressure ops



Conclusion:

Need to track to within 1 m if pressure is known to 0.5 mTorr



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Gas density fluctuations affect required tracking distance

	5 mTorr	10 mTorr	50 mTorr
5% Fluctuations	1.3 m (3.2 ms)	0.95 m (2.4 ms)	0.46 m (1.2 ms)
10% Fluctuations	0.95 m (2.4 ms)	0.66 m (1.65 ms)	0.33 m (0.83 ms)
50% Fluctuations	0.42 m (1.1 ms)	0.30 m (0.75 ms)	0.15 m (0.38 ms)

Assumptions:

Shot to shot chamber gas density is unknown to \pm fluctuation value

2 mm radius, 4 mg target moving 400 m/s

Target velocity is well measured

Xe gas drag ± 10 micron affect on target position

**Even 5% fluctuations of 5 mTorr chamber gas
requires tracking to within 1.3 m of chamber center**



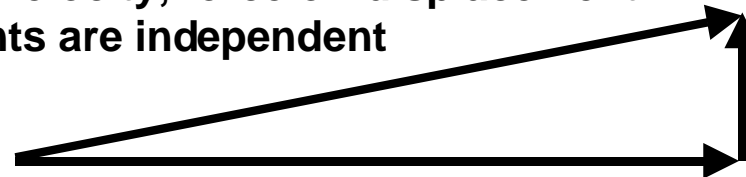
Windspeed fluctuations affect required tracking distance

Normalized wind speed	5 mTorr	10 mTorr	50 mTorr
5% Fluctuations	1.3 m (3.2 ms)	0.95 m (2.4 ms)	0.46 m (1.2 ms)
10% Fluctuations	0.95 m (2.4 ms)	0.66 m (1.65 ms)	0.33 m (0.83 ms)
50% Fluctuations	0.42 m (1.1 ms)	0.30 m (0.75 ms)	0.15 m (0.38 ms)

Same table applies as for gas density variations

Normalized wind speed is chamber gas speed divided by target speed

Resultant velocity, force or displacement components are independent



Force or displacement due to wind speed

Force or displacement due to target velocity

Assumptions:

2 mm radius, 4 mg target moving 400 m/s

Shot to shot normalized wind speed is unknown to \pm fluctuation value

Target velocity is well measured

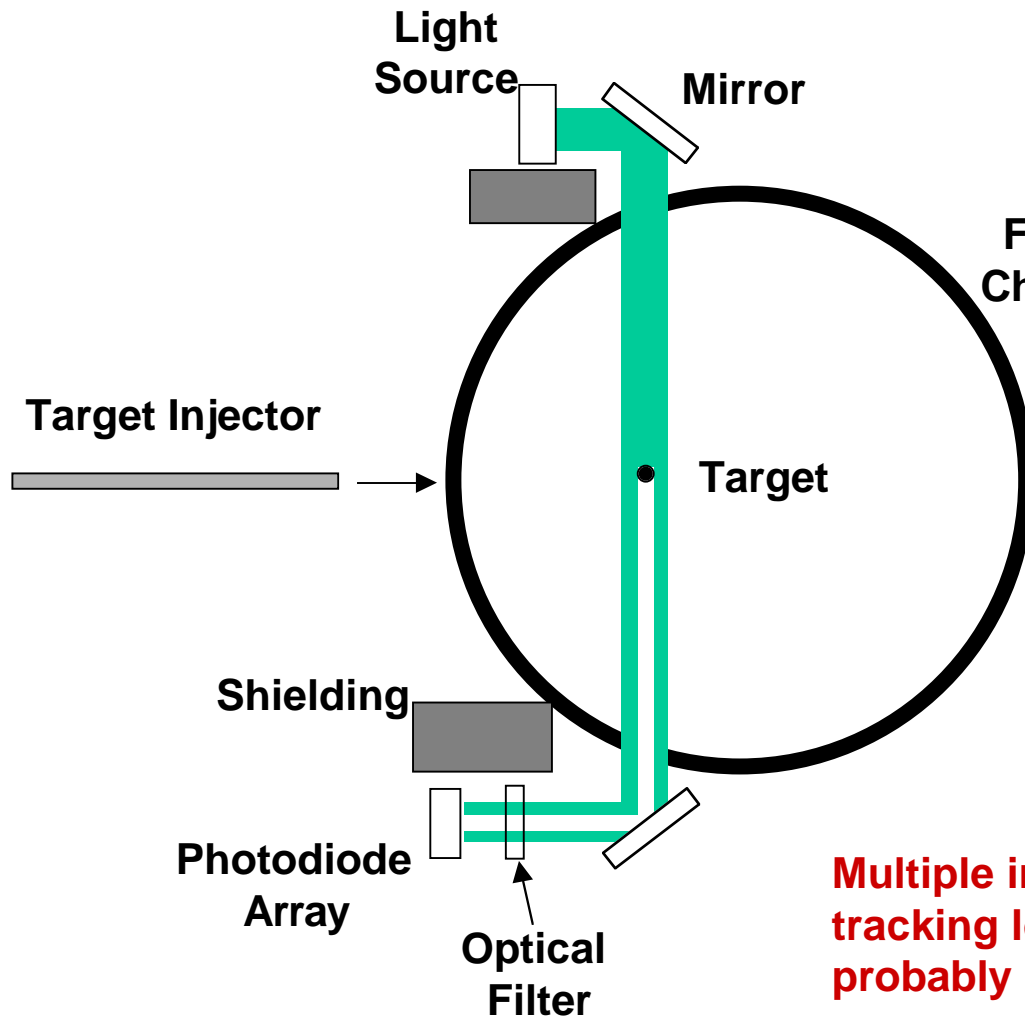
Unknown wind affect on drag has ± 10 micron affect on target position

Drag force is proportional to target velocity relative to chamber gas

(true for $< \sim 50$ mTorr gas and velocity $< \sim 400$ m/s)



Direct view of backlit target is the “baseline” in-chamber tracking method



Fresnel number is of order unity
so diffraction will be significant.

$$F = \frac{a^2}{\lambda R} \sim \frac{(2\text{mm})^2}{0.4\mu\text{m}(10\text{m})} = 1$$

In chamber tracking systems
utilize band pass optical filters to
minimize interference from hot
chamber radiation

Shadow cast by target
is measured by photodiode array
Beam path is shown rotated 90°

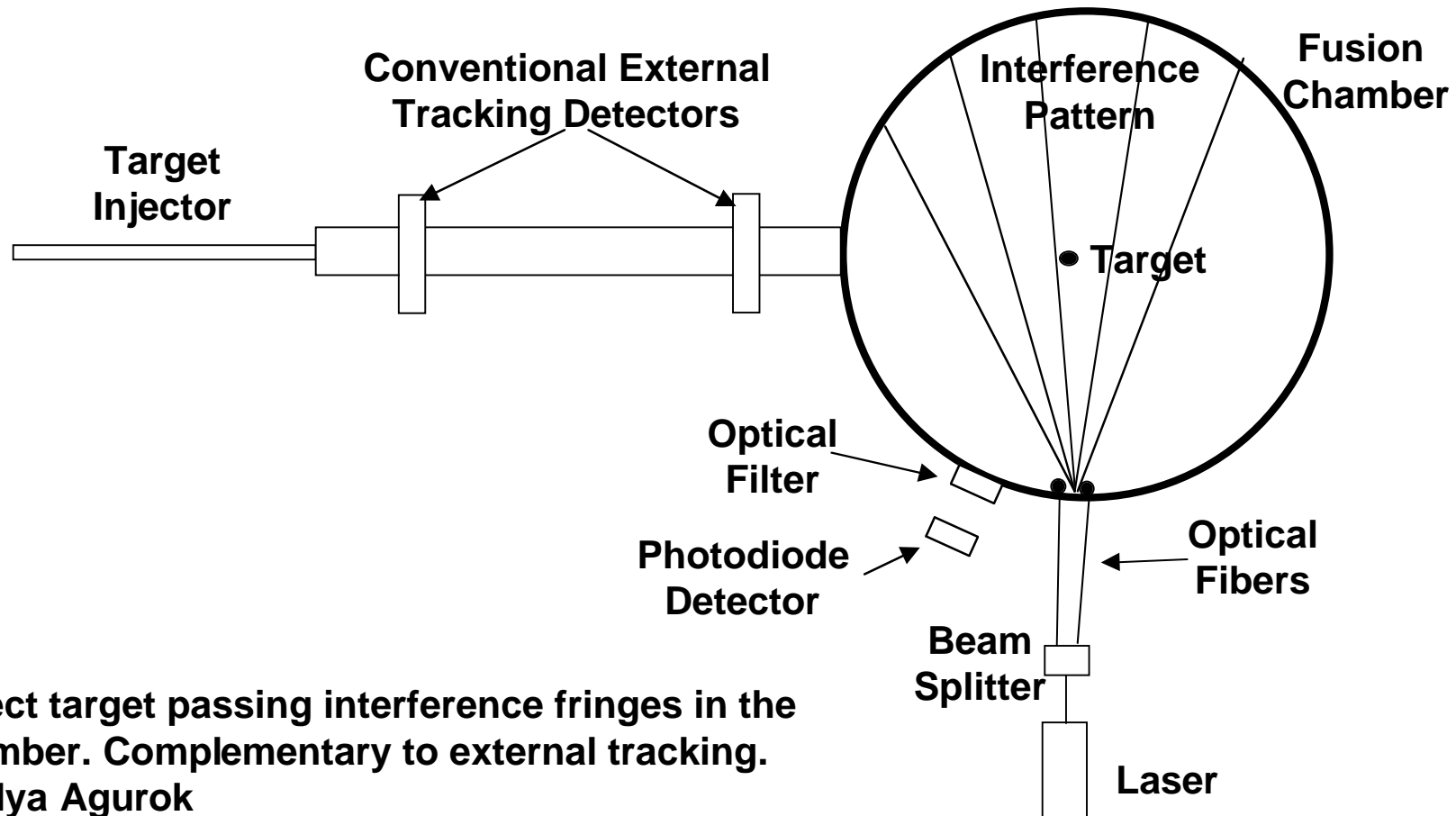
**Multiple in-chamber
tracking locations would
probably be used.**



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An interferometric tracking method may also be possible



Detect target passing interference fringes in the chamber. Complementary to external tracking.

Dr. Ilya Agurok

SBIR-Physical Optics Corporation, Torrance, CA



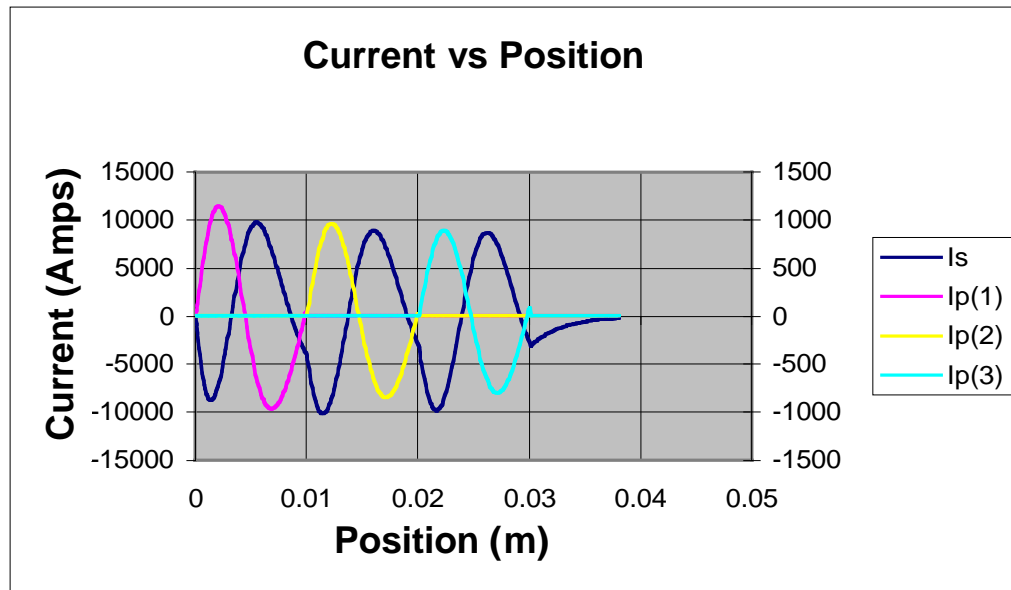
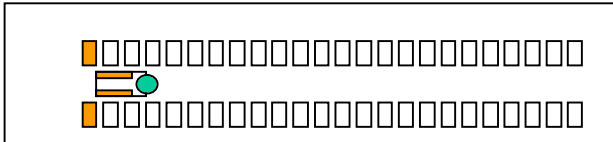
An electromagnetic injector has advantages for production use.

Being studied as a backup to the gas gun

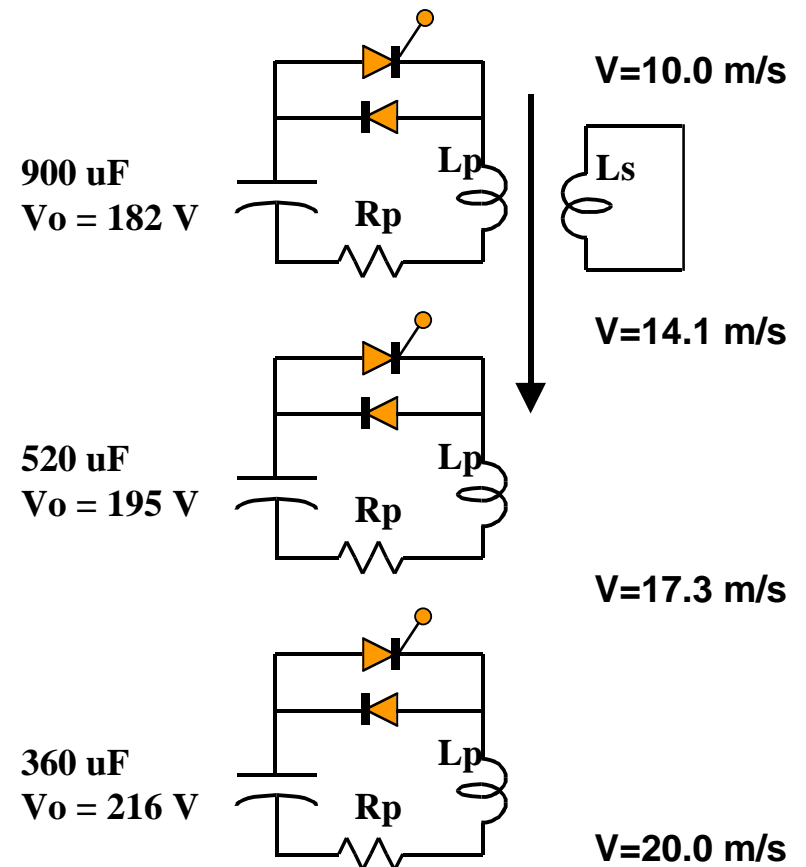
Advantage: Repulsive force allows potential for self centering low wear operation

Strategy: Computer modeling of injector operation to facilitate design.

Building small scale experiment to verify computer model IAW FY 99 plan



Opposite direction primary and secondary currents cause repulsive force





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Summary and Conclusions

Injection and tracking experimental design

- Project is proceeding on schedule
- The target injection and tracking system final design review is this Friday

In-chamber tracking

- External tracking of direct drive targets requires pressure known to $\sim 10^{-5}$ Torr
- 0.5 mTorr Xe pressure uncertainty requires tracking to 1 m from center (Direct Drive)
- A fractional change in normalized wind speed affects target trajectory same as an equivalent change in gas density
- “Baseline” in-chamber tracking is modified external method
 - Mirrors and optical filters will be added
 - Stand-off distance is greater implying more diffraction
- Interferometric target tracking is being investigated

Electromagnetic injector

- A non-contacting electromagnetic injector is being modeled as a backup to the gas gun